



## Main

Range of product	Lexium integrated drive
Product or component type	Motion integrated drive
Device short name	ILE
Motor type	Brushless dc motor
Number of motor poles	6
Network number of phases	Single phase
[Us] rated supply voltage	24 V 36 V
Network type	DC
Communication interface	Integrated Profibus DP
Length	174 mm
Winding type	Medium speed of rotation and medium torque
Electrical connection	Printed circuit board connector
Holding brake	Without
Gear box type	Straight teeth gear, 4 stages
Reduction ratio	115:1 (3675:32)
Nominal speed	42 rpm at 36 V 35 rpm at 24 V
Nominal torque	11 N.m at 36 V 10 N.m at 24 V

## Complementary

Transmission rate	9.6, 19.2, 45.45, 93.75, 187.5, 500, 1500, 3000, 6000 and 12000 kbauds
Mounting support	Flange
Motor flange size	66 mm
Number of motor stacks	1
Centring collar diameter	16 mm
Centring collar depth	4 mm
Number of mounting holes	4
Mounting holes diameter	4.4 mm
Circle diameter of the mounting holes	73.54 mm
Feedback type	BLDC encoder
Shaft end	Keyed
Second shaft	Without second shaft end
Shaft diameter	10 mm
Shaft length	25 mm
Key width	16 mm
Supply voltage limits	18...40 V
Current consumption	5500 mA (maximum continuous) 7000 mA (peak)
Associated fuse rating	10 A
Input/Output type	4 signals (each be used as input or output)
Voltage state 0 guaranteed	-3...4.5 V
Voltage state 1 guaranteed	15...30 V

Discrete input current	2 mA at 24 V for 24 V signal interface ≤ 3 mA at 24 V on/STO_B for safety input ≤ 10 mA at 24 V on/STO_A for safety input
Discrete output voltage	23...25 V
Maximum switching current	200 mA total 100 mA per output
Protection type	Overload of output voltage Safe torque off Short circuit of the output voltage
Supply current	Supply: 2.6 A, 24 V Supply: 2.1 A, 36 V Supply: 0.1 A, 24 V, power stage disabled Supply: 0.06 A, 36 V, power stage disabled
Nominal output power	48 W at 36 V 38 W at 24 V
Peak stall torque	20.7 N.m at 36 V 14.95 N.m at 24 V
Continuous stall torque	14 N.m
Detent torque	8 N.m
Speed feedback resolution	0.26° (gearbox output) 12 points/turn (motor)
Accuracy error	+/- 1 point
Torsional backlash	≤ 1 °
Rotor inertia	1962 kg.cm <sup>2</sup>
Maximum mechanical speed	44 rpm
Maximum radial force Fr	200 N (short-term operation) 200 N (long-term operation)
Maximum axial force Fa	80 N (short-term operation) 10 N (long-term operation)
Service life in hours	15000 h of bearing : (long-term operation) 2500 h of bearing : (short-term operation)
Marking	CE
Type of cooling	Natural convection
Product weight	1.85 kg

## Environment

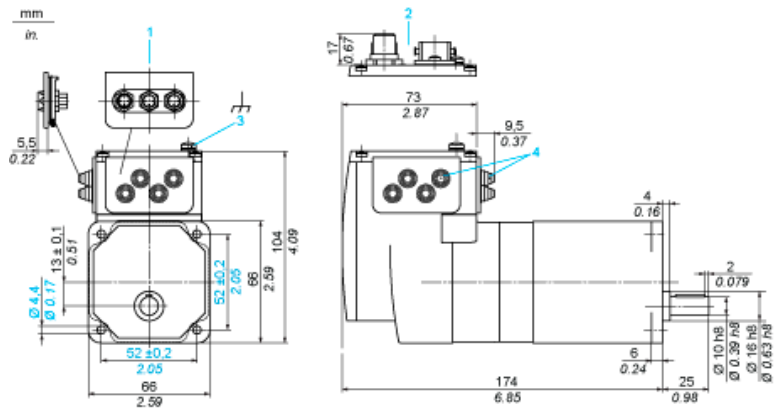
Standards	EN 50347 EN 61800-3:2001, second environment EN 61800-3 : 2001-02 EN/IEC 50178 EN/IEC 61800-3 IEC 60072-1 IEC 61800-3, Ed 2
Product certifications	CUL TÜV UL
Ambient air temperature for operation	0...50 °C without derating > 50...65 °C with power derating of 2 % per °C
Permissible ambient air temperature around the device	110 °C (motor) 105 °C (power amplifier)
Ambient air temperature for storage	-25...70 °C
Operating altitude	≤ 1000 m without derating
Relative humidity	15...85 % without condensation
Vibration resistance	20 m/s <sup>2</sup> (f = 10...500 Hz) for 10 cycles conforming to EN/IEC 60068-2-6
Shock resistance	150 m/s <sup>2</sup> for 1000 shocks conforming to EN/IEC 60068-2-29
IP degree of protection	IP54 total except shaft bushing conforming to EN/IEC 60034-5 IP41 shaft bushing conforming to EN/IEC 60034-5

## Offer Sustainability

Sustainable offer status	Green Premium product
RoHS (date code: YYWW)	Compliant - since 0922 - <a href="#">Schneider Electric declaration of conformity</a>
REACH	Reference not containing SVHC above the threshold
Product environmental profile	Available <a href="#">Download Product Environmental</a>
Product end of life instructions	Available <a href="#">Download End Of Life Manual</a>

Integrated Drive with Straight Teeth Gear

Dimensions

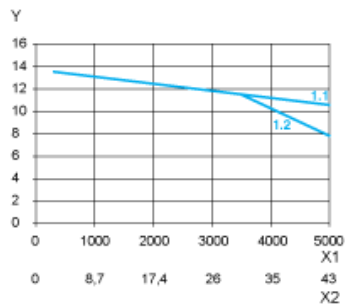


- 1 Accessories: I/O signal insert with industrial connectors
- 2 Option: industrial connectors
- 3 Earth (ground) terminal
- 4 Accessories: cable entries  $\varnothing = 3 \dots 9 \text{ mm} / 0.12 \dots 0.35 \text{ in.}$

## Connection Example with 4 I/O Signals



Torque Characteristics



- X1 Speed of rotation of motor in rpm
- X2 Speed of rotation of gearing in rpm
- Y Torque in Nm
- 1.1 Max. torque at 24 V
- 1.2 Max. torque at 36 V