

BMH0703T06A2A

servo motor BMH - 3.4 Nm - 8000 rpm -
untapped shaft - without brake - IP54



Main

Product or component type	Servo motor
Device short name	BMH
Maximum mechanical speed	8000 rpm
Continuous stall torque	3.4 N.m for LXM32.D30M2 10 A at 115 V single phase 3.4 N.m for LXM32.D18M2 6 A at 230 V single phase
Peak stall torque	8.7 N.m for LXM32.D30M2 10 A at 115 V single phase 10.2 N.m for LXM32.D18M2 6 A at 230 V single phase
Nominal output power	650 W for LXM32.D30M2 10 A at 115 V single phase 900 W for LXM32.D18M2 6 A at 230 V single phase
Nominal torque	3.1 N.m for LXM32.D30M2 10 A at 115 V single phase 2.9 N.m for LXM32.D18M2 6 A at 230 V single phase
Nominal speed	2000 rpm for LXM32.D30M2 10 A at 115 V single phase 3000 rpm for LXM32.D18M2 6 A at 230 V single phase
Product compatibility	LXM32.D30M2 at 115 V single phase LXM32.D18M2 at 230 V single phase
Shaft end	Untapped
IP degree of protection	IP54 (standard)
Speed feedback resolution	32768 points/turn
Holding brake	Without
Mounting support	International standard flange
Electrical connection	Rotatable right-angled connectors

Complementary

Range compatibility	Lexium 32
[Us] rated supply voltage	240 V
Network number of phases	Three phase
Continuous stall current	5.55 A
Continuous power	1.68 W
Maximum current Irms	15 A for LXM32.D30M2 17.8 A for LXM32.D18M2
Maximum permanent current	17.84 A
Second shaft	Without second shaft end
Shaft diameter	14 mm
Shaft length	30 mm
Feedback type	Single turn SinCos Hiperface
Motor flange size	70 mm
Number of motor stacks	3
Torque constant	0.61 N.m/A at 120 °C
Back emf constant	39.3 V/krpm at 120 °C

Number of motor poles	10
Rotor inertia	1.67 kg.cm ²
Stator resistance	1.32 Ohm at 20 °C
Stator inductance	4.3 mH at 20 °C
Stator electrical time constant	3.3 ms at 20 °C
Maximum radial force Fr	730 N at 1000 rpm 580 N at 2000 rpm 510 N at 3000 rpm 460 N at 4000 rpm 430 N at 5000 rpm 400 N at 6000 rpm
Maximum axial force Fa	0.2 x Fr
Type of cooling	Natural convection
Length	186 mm
Centring collar diameter	60 mm
Centring collar depth	2.5 mm
Number of mounting holes	4
Mounting holes diameter	5.5 mm
Circle diameter of the mounting holes	82 mm
Product weight	3 kg

Offer Sustainability

Sustainable offer status	Green Premium product
RoHS (date code: YYWW)	Compliant - since 0936 - Schneider Electric declaration of conformity
REACH	Reference not containing SVHC above the threshold
Product environmental profile	Available Download Product Environmental
Product end of life instructions	Need no specific recycling operations

Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)

Dimensions in mm

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)	c1	c2	c3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
39.5	25.5	39.5	39.5	186	225	30	20	5	5 h9	16 ⁺⁰ _{-0.13}	14 k6	M5 x 17

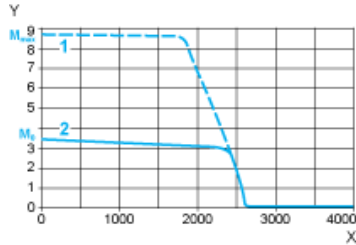
Dimensions in in.

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)	c1	c2	c3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
1.55	1	1.55	1.55	7.32	8.85	1.18	0.78	0.19	0.20 h9	0.63 ⁺⁰ _{-0.0051}	0.55 k6	M5 x 0.67

115 V Single-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D30M2 servo drive

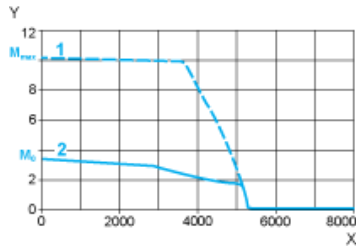


- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque

230 V Single-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18M2 servo drive



- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque