

Sure Cross® Wireless Q45VA and VAC All-in-One Vibration and Temperature Node



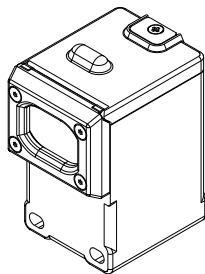
Datasheet

The Wireless Q45VA / Q45VAC All-in-One Sensor Node combines Banner's VT1 Vibration and Temperature Sensor with the Sure Cross® Q45VT Wireless Sensor Node. The Q45VA / VAC is a compact, industrial, battery-powered device that wirelessly communicates with any Sure Cross Performance Gateway on a variety of machines to analyze vibration and temperature data to identify and predict failures in rotating machinery.

Benefits

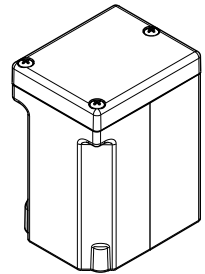
- Delivers pre-processed high accuracy vibration values for monitoring rotating equipment such as:
 - Motors
 - Pumps
 - Rotary Compressors
 - Exhaust or HVAC fan motors
 - Spindles
- Easy-to-use rugged device that can be easily mounted to equipment
- Use with the DXM Wireless Controller to track and trend vibration and temperature characteristics in real time to predict need for maintenance, predict potential component failure and avoid process downtime.
- Battery powered for “peel and stick” functionality with 2+ years of battery life
- Detects vibration characteristics on 2 axis (radial and axial) such as RMS Velocity, High Frequency Acceleration, Peak Acceleration, Peak Velocity Component Frequency, etc.
- Achieves vibration accuracy of $\pm 10\%$ RMS velocity (in/sec)
- **Eliminate control wires**—The Sure Cross wireless system is a radio frequency network with integrated I/O that removes the need for power and control wires
- **Reduce complexity**—Machine or process reconfiguration made easier; great for retrofit applications
- **Deploy easily**—Simplifying installation on existing equipment enables deployment in remote and hard-to-access locations where implementing a wired solution would be difficult, impractical, or not cost-effective

Figure 1. Q45VA



- Transmit power levels of 250 mW or 1 Watt for 900 MHz models and 65 mW for 2.4 GHz models are user-selectable
- DIP switches for user configuration of sample time and vibration characteristics
- Frequency Hopping Spread Spectrum (FHSS) technology ensures reliable data delivery
- Transceivers provide bidirectional communication between the Gateway and Node, including fully acknowledged data transmission
- Diagnostics allow user-defined output settings in the unlikely event of lost RF signal

Figure 2. Q45VAC



Models

| Models | Power | Frequency | Inputs and Outputs | Other |
|-----------------|--------------------------|-----------|-------------------------------------|--|
| DX80N2Q45VA | Two Lithium AA Batteries | 2.4 GHz | Vibration and temperature detection | Includes batteries |
| DX80N2Q45VA-NB | | | | No batteries included |
| DX80N9Q45VA | | 900 MHz | | Includes batteries |
| DX80N9Q45VA-NB | | | | No batteries included |
| DX80N9Q45VA-BK | | | | Includes batteries and BWA-BK-009 and BWA-BK-010 mounting brackets |
| DX80N2Q45VAC | C-cell Battery | 2.4 GHz | | Includes batteries |
| DX80N2Q45VAC-NB | | | | No battery included |
| DX80N9Q45VAC | | 900 MHz | | Includes battery |
| DX80N9Q45VAC-NB | | | | No battery included |
| DX80N9Q45VAC-BK | | | | Includes battery and BWA-BK-025 and BWA-BK-026 mounting brackets |



Storage Mode

While in **storage mode**, the device's radio does not operate, to conserve the battery. To put any device into storage mode, press and hold the binding button for five seconds. The device is in storage mode when the LEDs stop blinking. To wake the device, press and hold the binding button (inside the housing on the radio board) for five seconds.

General Operation

For the first 15 minutes after power up, the Node samples the sensor every two seconds (fast sample mode). After 15 minutes, the Node defaults to five-minute sample intervals. Activate fast sample mode by single clicking the button (the amber LED is solid).

ISO 10816 provides guidance for evaluating vibration velocity severity motors, pumps, fans, compressors, gear boxes, blowers, dryers, presses, and other machines that operate in the 10 to 1000 Hz frequency range.

Figure 3. Vibration Severity per ISO 10816

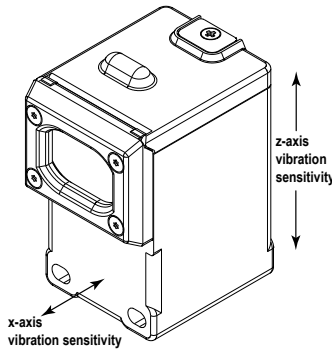
| Vibration Velocity Vrms | Machine | | Class I | Class II | Class III | Class IV |
|-------------------------|---------|------|----------------|-----------------|------------------------|-----------------------|
| | in/s | mm/s | Small Machines | Medium Machines | Large Rigid Foundation | Large Soft Foundation |
| 0.01 | 0.28 | | | | | |
| 0.02 | 0.45 | | | | | |
| 0.03 | 0.71 | | | good | | |
| 0.04 | 1.12 | | | | | |
| 0.07 | 1.80 | | | | | |
| 0.11 | 2.80 | | | satisfactory | | |
| 0.18 | 4.50 | | | | | |
| 0.28 | 7.10 | | | unsatisfactory | | |
| 0.44 | 11.2 | | | | | |
| 0.70 | 18.0 | | | | | |
| 1.10 | 28.0 | | | unacceptable | | |
| 1.77 | 45.9 | | | | | |

Button and LEDs



1. Button
2. Red LED (flashing) indicates a radio link error with the Gateway.
3. Green LED (flashing) indicates a good radio link with the Gateway.
4. Amber LED is not used.
5. DIP Switches

Installing the Q45VA



The vibration sensors have an x- and z-axis indication on the face of the sensor.

- Install the x-axis in line with the shaft of the motor or axially.
- Install the z-axis to go into or through the motor or radial.

For the best results, install the sensor as close to the motor bearing as possible. If this is not possible, install the sensor on a surface that is in rigid connection with vibration characteristics of the motor. Using a cover shroud or other flexible mounting location may result in reduced accuracy or reduced ability to detect certain vibration characteristics.

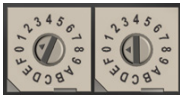
The Q45VA body can be affixed to the motor using Loctite 330 and 7387 Activator or similar two-part epoxy. For information about optional brackets, see [Brackets / Installation for the Q45VA](#) on page 10.

Configuration Instructions

Bind to the Gateway and Assign the Node Address

Before beginning the binding procedure, apply power to all the devices. Separate the devices by two meters when running binding procedure. Put only one Gateway into binding at a time to prevent binding to the wrong Gateway.

1. On the Gateway: Enter binding mode.
 - For housed DX80 Gateways, triple-click button 2 on the Gateway. Both LEDs flash red.
 - For Gateway board modules, triple-click the button. The green and red LED flashes.
2. Assign the Q45VA / VAC a Node address using the Gateway's rotary dials. Use the left rotary dial for the left digit and the right rotary dial for the right digit. For example, to assign your Q45VA / VAC to Node 10, set the Gateway's left dial to 1 and the right dial to 0. Valid Node addresses are 01 through 47.



3. On the Q45: Loosen the clamp plate on the top of the Q45VA / VAC and lift the cover.
4. Enter binding mode on the Q45VA / VAC by triple-clicking the Q45VA / VAC's button. The red and green LEDs flash alternately and the sensor searches for a Gateway in binding mode. After the Q45VA / VAC is bound, the LEDs stay solid momentarily, then they flash together four times. The Q45VA / VAC exits binding mode.
5. Label the sensor with the Q45VA / VAC's Node address number for future reference.
6. Repeat steps 2 through 5 for as many Q45VA / VACs as are needed for your network.
7. On the Gateway: After binding all Q45VA / VACs, exit binding mode.
 - For housed DX80 Gateways, double-click button 2.
 - For board-level DX80 Gateways, double-click the button.

For Gateways with single-line LCDs: After binding your Q45VA / VAC to the Gateway, make note of the binding code displayed under the Gateway's *DVCFG menu, XADR submenu on the LCD. Knowing the binding code prevents having to re-bind all Q45VA / VACs if your Gateway is ever replaced.

Bind to a DXM and Assign the Node Address

Before beginning the binding procedure, apply power to all the devices. Separate the radios by two meters when running the binding procedure. Put only one DXM into binding mode at a time to prevent the Q45VA / VAC from binding to the wrong Gateway.

1. On the DXM: Use the arrow keys to select the **ISM Radio** menu on the LCD and click **ENTER**.
2. Highlight the **Binding** menu and click **ENTER**.
3. Use the arrow keys to select the Node address to bind the Q45VA / VAC to.
4. On the Q45VA / VAC: Loosen the top clamp plate and lift the cover.
5. Enter binding mode by triple-clicking the binding button. The red and green LEDs flash alternately and the sensor searches for a Gateway in binding mode. After the Node binds, the LEDs stay solid momentarily, then they flash together four times. The Node exits binding mode.
6. Label the sensor with the Node address number for future reference.
7. On the DXM: Click **BACK** to exit binding for that specific Node address.

8. Repeat steps 3 through 7 and change the Node address for as many Q45VA / VACs as are needed for your network.
9. On the DXM: After you have finished forming your network, click **BACK** until you reach the main menu.

DIP Switches

After making any changes to any DIP switch position, reboot the Q45VA / VAC by triple-clicking the button, waiting a second, then double-clicking the button.

The DIP switches are in the OFF position. To turn a DIP switch on, push the switch toward the battery pack. DIP switches one through four are numbered from left to right.

Table 1: DIP switch settings

| Description | DIP Switches | | | | | | | |
|--|--------------|------|------|------|------|------|------|------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| Transmit power: 1 Watt (default setting) | OFF* | | | | | | | |
| Transmitt power: 250 mW (compatible with 150 mW radios) | ON | | | | | | | |
| Default I/O Configuration (default setting) ¹ | | OFF* | OFF* | OFF* | | | | |
| I/O Configuration 1 | | OFF | OFF | ON | | | | |
| I/O Configuration 2 | | OFF | ON | OFF | | | | |
| I/O Configuration 3 | | OFF | ON | ON | | | | |
| I/O Configuration 4 | | ON | OFF | OFF | | | | |
| I/O Configuration 5 | | ON | OFF | ON | | | | |
| Reserved | | ON | ON | OFF | | | | |
| Reserved | | ON | ON | ON | | | | |
| Sample/Report Rate: User configured (5 minutes by default) (default setting) | | | | | OFF* | OFF* | | |
| Sample/Report Rate: 150 seconds | | | | | OFF | ON | | |
| Sample/Report Rate: 60 seconds | | | | | ON | OFF | | |
| Reserved | | | | | ON | ON | | |
| English Units (in/s and °F) (default setting) | | | | | | | OFF* | |
| Metric Units (mm/s and °C) | | | | | | | ON | |
| Reserved (default setting) | | | | | | | | OFF* |

Table 2: I/O Configurations (Set by DIP Switches 2, 3, and 4)

| Input Register | | Default I/O | I/O Configuration 1 | I/O Configuration 2 | I/O Configuration 3 | I/O Configuration 4 | I/O Configuration 5 |
|----------------|--------|-------------------------------------|-----------------------|-------------------------------------|--|--------------------------------------|-------------------------------------|
| 1 | Z-Axis | RMS Velocity (in/sec) | RMS Velocity (in/sec) | High-Frequency RMS Acceleration (G) | RMS Velocity (in/sec) | Full Bandwidth RMS Acceleration (G) | RMS Velocity (in/sec) |
| 2 | | High-Frequency RMS Acceleration (G) | Peak Acceleration (G) | Peak Acceleration (G) | Peak Velocity Component Frequency (Hz) | Full Bandwidth Peak Acceleration (G) | Full Bandwidth RMS Acceleration (G) |
| 3 | - | Temperature (°F) | Temperature (°F) | Temperature (°F) | Temperature (°F) | Temperature (°F) | Temperature (°F) |
| 4 | - | Reserved | Reserved | Reserved | Reserved | Reserved | Reserved |
| 5 | X-Axis | RMS Velocity (in/sec) | RMS Velocity (in/sec) | High-Frequency RMS Acceleration (G) | RMS Velocity (in/sec) | Full Bandwidth RMS Acceleration (G) | RMS Velocity (in/sec) |
| 6 | | High-Frequency RMS Acceleration (G) | Peak Acceleration (G) | Peak Acceleration (G) | Peak Velocity Component Frequency (Hz) | Full Bandwidth Peak Acceleration (G) | Full Bandwidth RMS Acceleration (G) |

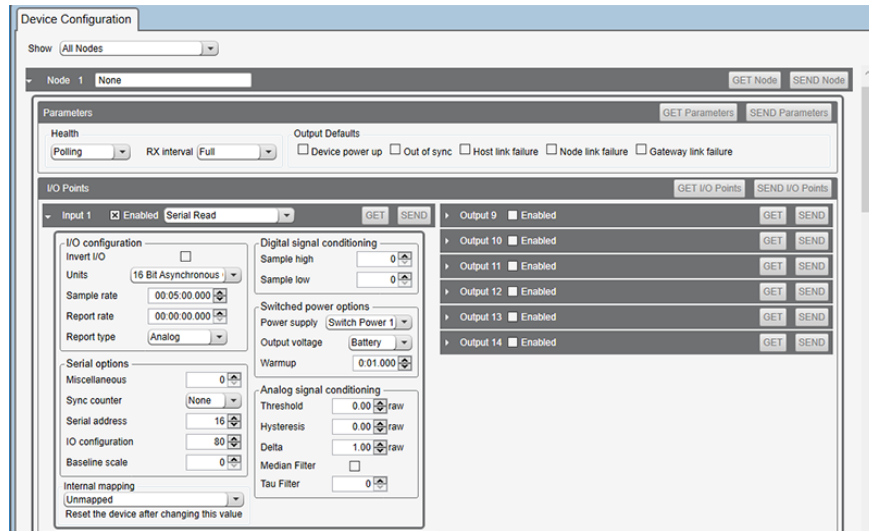
If DIP switch 7 is on, all in/s units change to mm/s. DIP switch 7 will only switch units with DIP switch I/O configurations, not with any user configuration.

Configure the Q45 Using the User Configuration Software

The User Configuration Software offers an easy way to change sensor settings, show sensor data from different sensors, and retrieve data from the Gateway radio. The software runs on any Windows computer and uses an adapter cable to connect the Gateway to your computer.

Download the most recent version of the software from Banner Engineering's website: www.bannerengineering.com/wireless.

¹ User configurable if switch 7 is OFF; for input serial addresses, see [Modbus Registers and I/O Serial Addresses](#) on page 5



1. Go to the **Configuration > Device Configuration** screen.
2. On the top of the screen, select **Nodes Currently in the System** from the drop-down list and click **Get devices in system**. All Nodes bound to the Gateway connected to the computer display.
3. Click the arrow next to the Nodes to display the parameters specific to that Node. In this example, the parameters for Node 1 are shown.
4. Under the Node 1 I/O points section, click **GET I/O Points**. All I/O types for this Node are loaded onto the screen.
5. To view the parameters for an I/O point, click the arrow next to that I/O point. In this example, the parameters for I/O point 1 are shown.
6. To set the **Serial address**, go to the **Serial options** section of the I/O point's parameters and enter the value. In this example, the **Serial address** is set to 16 for output Z-Axis RMS Velocity (in/sec).
7. After making changes to the I/O point parameters, click **SEND** to send the changes to the network.
8. Repeat steps 5 and 8 for each input to manually change the configuration of the vibration parameters by changing the serial address.

For more information on using the User Configuration Software, refer to the instruction manual (p/n [140628](#)).

Modbus Registers and I/O Serial Addresses

Table 3: I/O serial addresses

| Serial Address | Output Type | I/O Range | | Holding Register Representation | |
|----------------|---|-----------|--------|---------------------------------|-----------|
| | | Min | Max | Min (Dec) | Max (Dec) |
| 16 | Z-Axis RMS Velocity (in/sec) ^{1, 5} | 0 | 6.5535 | 0 | 65535 |
| 25 | Z-Axis High-Frequency RMS Acceleration ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| - | Reserved | - | - | - | - |
| 64 | X-Axis RMS Velocity (in/sec) ^{1, 5} | 0 | 6.5535 | 0 | 65535 |
| 73 | X-Axis High-Frequency RMS Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 20 | Z-Axis Peak Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 68 | X-Axis Peak Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 18 | Z-Axis Peak Velocity Component Frequency (Hz) ^{4, 5} | 0 | 6553.5 | 0 | 65535 |
| 66 | X-Axis Peak Velocity Component Frequency (Hz) ^{4, 5} | 0 | 6553.5 | 0 | 65535 |
| 19 | Z-Axis RMS Acceleration (G) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 67 | X-Axis RMS Acceleration (G) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 24 | Z-Axis Kurtosis ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 72 | X-Axis Kurtosis ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 37 | Z-Axis Crest Factor ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 69 | X-Axis Crest Factor ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 17 | Z-Axis Peak Velocity (in/sec) ^{1, 5} | 0 | 6.5535 | 0 | 65535 |
| 23 | Z-Axis Peak Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |

| Serial Address | Output Type | I/O Range | | Holding Register Representation | |
|----------------|---|-----------|--------|---------------------------------|-----------|
| | | Min | Max | Min (Dec) | Max (Dec) |
| 65 | X-Axis Peak Velocity (in/sec) ^{1, 5} | 0 | 6.5535 | 0 | 65535 |
| 71 | X-Axis Peak Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 22 | Z-Axis RMS Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 70 | X-Axis RMS Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 27 | Full Bandwidth RMS Acceleration Z-Axis (G) ^{2, 7} | 0 | 65.535 | 0 | 65535 |
| 75 | Full Bandwidth RMS Acceleration X-Axis (G) ^{2, 7} | 0 | 65.535 | 0 | 65535 |
| 28 | Full Bandwidth Peak Acceleration Z-Axis (G) ^{2, 7} | 0 | 65.535 | 0 | 65535 |
| 76 | Full Bandwidth Peak Acceleration X-Axis (G) ^{2, 7} | 0 | 65.535 | 0 | 65535 |
| 192 | Temperature (°C) ³ | -1638.4 | 1638.4 | -32768 | 32767 |
| 193 | Temperature (°F) ³ | -1638.4 | 1638.4 | -32768 | 32767 |

- ¹ Value = Register value ÷ 10000
- ² Value = Register value ÷ 1000
- ³ Value = Register value ÷ 20
- ⁴ Value = Register value ÷ 10

- ⁵ Measurement bandwidth = 10 Hz to 1 kHz
- ⁶ Measurement bandwidth = 1 kHz to 4 kHz
- ⁷ Measurement Bandwidth = 10 Hz to 4 kHz

Table 4: Modbus holding registers

| I/O # | Modbus Holding Register | | I/O Type | I/O Range | | Holding Register Representation | |
|-------|-------------------------|-------------------|-------------------------|-----------|------|---------------------------------|------|
| | Gateway | Any Node | | Min. | Max. | Min. | Max. |
| 1 | 1 | 1 + (Node# × 16) | Sensor Input Register 1 | | | | |
| 2 | 2 | 2 + (Node# × 16) | Sensor Input Register 2 | | | | |
| 3 | 3 | 3 + (Node# × 16) | Sensor Input Register 3 | | | | |
| 4 | 4 | 4 + (Node# × 16) | Sensor Input Register 4 | | | | |
| 5 | 5 | 5 + (Node# × 16) | Sensor Input Register 5 | | | | |
| 6 | 6 | 6 + (Node# × 16) | Sensor Input Register 6 | | | | |
| 7 | 7 | 7 + (Node# × 16) | Reserved | | | | |
| 8 | 8 | 8 + (Node# × 16) | Device Message | | | | |
| | | ... | | | | | |
| 15 | 15 | 15 + (Node# × 16) | Control Message | | | | |
| 16 | 16 | 16 + (Node# × 16) | Reserved | | | | |

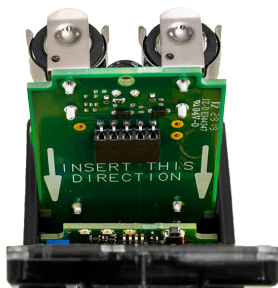
By default, data is supplied to the Node every five minutes, unless the Node requests the data sooner. The default configuration is shown and all optional outputs types are listed. Use the User Configuration Software to adjust the Sensor Register output type. Temperature values outside the operating range of the device are forced to the maximum or minimum values.

Apply Power to the Q45

Follow these instructions to install or replace the lithium "AA" cell batteries.

As with all batteries, these are a fire, explosion, and severe burn hazard. Do not burn or expose them to high temperatures. Do not recharge, crush, disassemble, or expose the contents to water. Properly dispose of used batteries according to local regulations by taking it to a hazardous waste collection site, an e-waste disposal center, or other facility qualified to accept lithium batteries.

Figure 4. Q45 battery board



1. Loosen the clamp plate with a small Phillips screwdriver and lift the cover.
2. Slide the battery board out of the Q45 housing.
3. If applicable, remove the discharged batteries.
4. Install the new batteries. Use Banner's **BWA-BATT-006** replacement batteries or an equivalent 3.6 V AA lithium batteries, such as Xeno's XL-60F.
5. Verify the battery's positive and negative terminals align to the positive and negative terminals of the battery holder mounted within the case. Caution: There is a risk of explosion if the battery is replaced incorrectly.
6. Slide the board containing the new batteries back into the Q45 housing.
7. Close the cover and gently tighten the clamp plate with the small Phillips screwdriver.

Apply Power to the Q45 C-Cell Models

Follow these instructions to install or replace the lithium C cell batteries.

Figure 5. Q45 battery board for c-cell batteries



As with all batteries, these are a fire, explosion, and severe burn hazard.

Do not burn or expose them to high temperatures. Do not recharge, crush, disassemble, or expose the contents to water.

Properly dispose of used batteries according to local regulations by taking it to a hazardous waste collection site, an e-waste disposal center, or other facility qualified to accept lithium batteries.

1. Lift the plastic cover.
2. Slide the board containing the batteries out of the Q45 housing.
3. Remove the discharged battery and replace with new battery.

The replacement battery model number is **BWA-BATT-013**. For pricing and availability, contact Banner Engineering.

4. Verify the battery's positive and negative terminals align to the positive and negative terminals of the battery holder mounted within the case.

Caution: There is a risk of explosion if the battery is replaced incorrectly.

5. Slide the board containing the new batteries back into the Q45 housing.

Specifications

Performance Radio with Internal Antenna Specifications

Radio Range²

900 MHz, 1 Watt: Up to 3.2 km (2 miles) with line of sight (internal antenna)
2.4 GHz, 65 mW: Up to 1000 m (3280 ft) with line of sight (internal antenna)

Antenna Minimum Separation Distance

900 MHz, 150 mW and 250 mW: 2 m (6 ft)
900 MHz, 1 Watt: 4.57 m (15 ft)
2.4 GHz, 65 mW: 0.3 m (1 ft)

Radio Transmit Power

900 MHz, 1 Watt: 30 dBm (1 W) conducted (up to 36 dBm EIRP)
2.4 GHz, 65 mW: 18 dBm (65 mW) conducted, less than or equal to 20 dBm (100 mW) EIRP

Link Timeout (Performance)

Gateway: Configurable via User Configuration Software
Node: Defined by Gateway

Spread Spectrum Technology

FHSS (Frequency Hopping Spread Spectrum)

900 MHz Compliance (1 Watt)

FCC ID UE3RM1809: FCC Part 15, Subpart C, 15.247
IC: 7044A-RM1809
IFT: RCPBARM13-2283



(NOM approval only applies to 900 MHz models)

2.4 GHz Compliance

FCC ID UE300DX80-2400: FCC Part 15, Subpart C, 15.247
Radio Equipment Directive (RED) 2014/53/EU
IC: 7044A-DX8024

ANATEL: 15966-21-04042 Este equipamento não tem direito à proteção contra interferência prejudicial e não pode causar interferência em sistemas devidamente autorizados. Para maiores informações, consulte o site da ANATEL www.gov.br/anatel/pt-br/

² Range depends on the environment and decreases significantly without line of sight. Always verify your wireless network's range by performing a Site Survey.

Q45VA Sensor Specifications

Default Sensing Interval

5 minutes

Indicators

Red and green LEDs (radio function)

Construction

Molded reinforced thermoplastic polyester housing, oring-sealed transparent Lexan® cover, molded acrylic lenses, and stainless steel hardware. Designed to withstand 1200 psi washdown.

Shock

400G

Environmental Rating

NEMA 6P, IP67

Typical Battery Life

See chart.

Vibration Sensor

Measuring Range: 0 to 46 mm/sec or 0 to 1.8 in/sec RMS

Frequency Range: 10 Hz to 4 kHz

Accuracy: ±10% at 25 °C

Sampling Frequency: 20 kHz (default)

Record Length: 8192 points (default)

Sample Duration: 0.4 s (default)

Operating Conditions

Ambient temperature: -40 °C to +70 °C (-40 °F to +158 °F)

Contact temperature: -40 °C to +105 °C (-40 °F to +221 °F)

90% at +50 °C maximum relative humidity (non-condensing)

Radiated Immunity HF: 10 V/m (EN 61000-4-3)

Temperature Sensor

Measuring Range: -40 °C to +105 °C (-40 °F to +221 °F)

Dimensions

All measurements are listed in millimeters, unless noted otherwise.

Figure 6. Q45VA

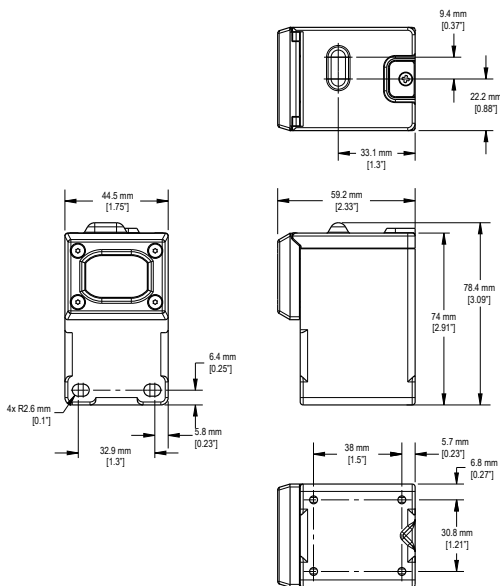
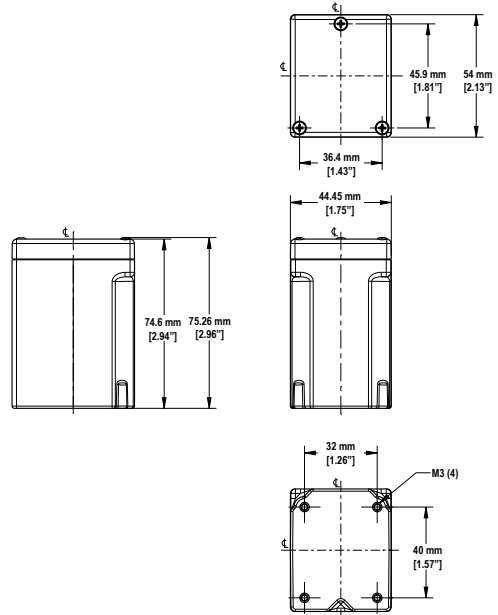


Figure 7. Q45VAC



Battery Life

Figure 8. Q45VA

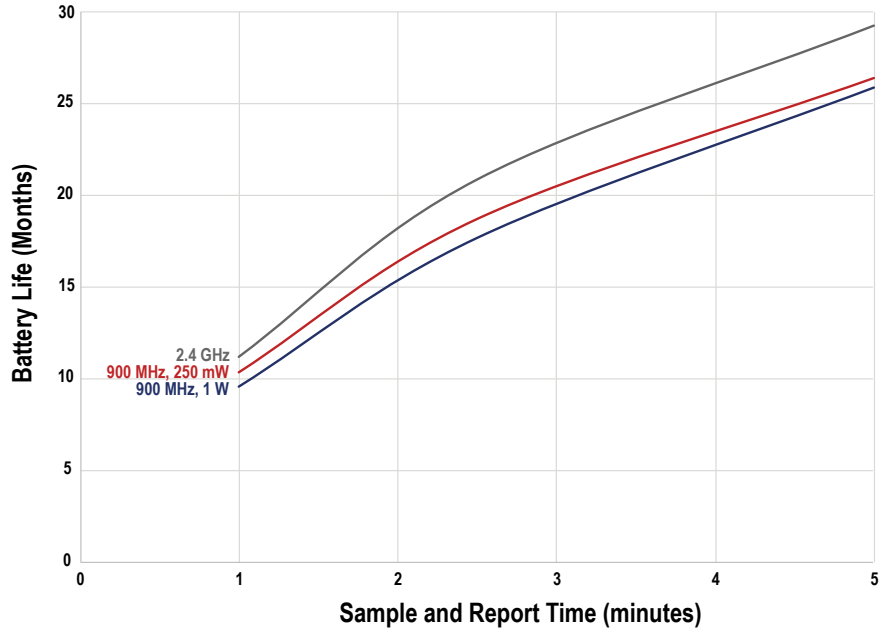
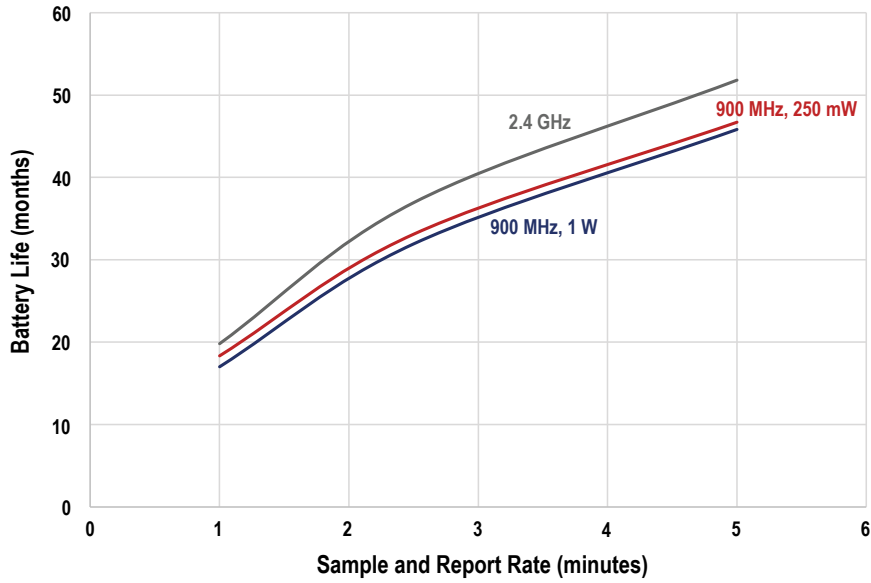


Figure 9. Q45VAC

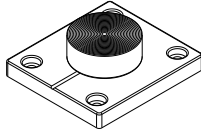


Accessories

Brackets / Installation for the Q45VA

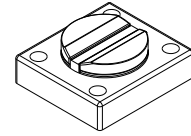
BWA-BK-009

- Mounts the device to a surface using two-part epoxy
- Alignment mark indicates the front of device
- Includes a base plate, two screw retainers, four mounting screws, a set screw, and a mounting disc
- 44.5 mm × 49.5 mm
- **For installation instructions, see Q45VA Bracket Assembly Quick Start Guide (p/n 208986)**



BWA-BK-010

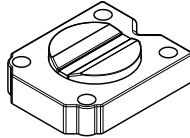
- Includes a magnetic mounting bracket and four mounting screws
- 44.5 mm × 49.5 mm
- SmCo magnet with a 40 lb pull strength
- For use on flat or curved surfaces



Brackets / Installation for the Q45VAC

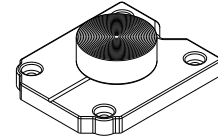
BWA-BK-025

- Includes a magnetic mounting bracket and four mounting screws
- For use on flat or curved surfaces
- SmCo magnet with a 40 lb pull strength
- 44.5 mm × 54 mm; 15.6 mm thick



BWA-BK-026

- Includes a base plate, two screw retainers, four mounting screws, a set screw, and a mounting disc
- Mounts the device to a surface using two-part epoxy
- Alignment mark indicates the front of device
- 44.5 mm × 54 mm



Warnings

Exporting Sure Cross® Radios. It is our intent to fully comply with all national and regional regulations regarding radio frequency emissions. **Customers who want to re-export this product to a country other than that to which it was sold must ensure the device is approved in the destination country.** The Sure Cross wireless products were certified for use in these countries using the antenna that ships with the product. When using other antennas, verify you are not exceeding the transmit power levels allowed by local governing agencies. This device has been designed to operate with the antennas listed on Banner Engineering's website and having a maximum gain of 9 dBm. Antennas not included in this list or having a gain greater than 9 dBm are strictly prohibited for use with this device. The required antenna impedance is 50 ohms. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen such that the equivalent isotropically radiated power (EIRP) is not more than that permitted for successful communication. Consult with Banner Engineering Corp. if the destination country is not on this list.



Important: Please download the complete Wireless Q45VA / Q45VAC All-in-One Sensor Node technical documentation, available in multiple languages, from www.bannerengineering.com for details on the proper use, applications, Warnings, and installation instructions of this device.



Important: Por favor descargue desde www.bannerengineering.com toda la documentación técnica de los Wireless Q45VA / Q45VAC All-in-One Sensor Node, disponibles en múltiples idiomas, para detalles del uso adecuado, aplicaciones, advertencias, y las instrucciones de instalación de estos dispositivos.



Important: Veuillez télécharger la documentation technique complète des Wireless Q45VA / Q45VAC All-in-One Sensor Node sur notre site www.bannerengineering.com pour les détails sur leur utilisation correcte, les applications, les notes de sécurité et les instructions de montage.

**WARNING:**

- **Do not use this device for personnel protection**
- Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A device failure or malfunction can cause either an energized (on) or de-energized (off) output condition.

**Important:**

- **Electrostatic discharge (ESD) sensitive device**
- ESD can damage the device. Damage from inappropriate handling is not covered by warranty.
- Use proper handling procedures to prevent ESD damage. Proper handling procedures include leaving devices in their anti-static packaging until ready for use; wearing anti-static wrist straps; and assembling units on a grounded, static-dissipative surface.

Banner Engineering Corp. Limited Warranty

Banner Engineering Corp. warrants its products to be free from defects in material and workmanship for one year following the date of shipment. Banner Engineering Corp. will repair or replace, free of charge, any product of its manufacture which, at the time it is returned to the factory, is found to have been defective during the warranty period. This warranty does not cover damage or liability for misuse, abuse, or the improper application or installation of the Banner product.

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For patent information, see www.bannerengineering.com/patents.

Notas Adicionales

Información México: La operación de este equipo está sujeta a las siguientes dos condiciones: 1) es posible que este equipo o dispositivo no cause interferencia perjudicial y 2) este equipo debe aceptar cualquier interferencia, incluyendo la que pueda causar su operación no deseada.

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Mexican Importer

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San Pedro Garza Garcia Nuevo León, C. P. 66269
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