



## Absolute encoders AFS/AFM60 SSI

AFM60B-TETA004096

**Model Name** > [AFM60B-TETA004096](#)  
**Part No.** > [1053521](#)



**At a glance**

- High-resolution absolute encoders with up to 30 bits (AFM60) or up to 18 bits (AFS60)
- Face mount flange, servo flange, blind or through hollow shaft
- SSI, SSI + Incremental or SSI + Sin/Cos interface
- Programmable resolution and offset (dependent on type)
- Connection system: M12, M23 connector or cable outlet
- Enclosure rating: IP 67 (housing), IP 65 (shaft)
- Operating temperature: -30 °C to +100 °C (depends on type)

**Your benefits**

- Programmability of the encoders means less storage, greater machine availability and easy installation
- Precise positioning due to high resolutions
- Large selection of mechanical interfaces and electrical contacting possibilities: Suitable for all applications
- Suitable for applications with limited space requirements (extremely short installation depth of 30 mm)
- Very good rotation accuracy due to increased bearing distance
- One programming tool and software with automatic encoder detection for AFS60/AFM60/DFS60



**Performance**

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Max. number of steps per revolution:	4,096
Max. number of revolutions:	4,096
Resolution power:	4,096 x 4,096
Resolution:	12 bit x 12 bit
Error limits:	± 0.05 °
Repeatability (Ta not constant):	0.002 °
Measuring step deviation:	± 0.01 °
Measuring step:	90 ° elektrisch/Strichzahl
Initialization time:	50 ms <sup>1)</sup>

<sup>1)</sup> Valid positional data can be read once this time has elapsed

**Mechanical data**

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Mechanical interface:	Through hollow shaft
Shaft diameter:	12 mm

Mass:	0.2 kg
Start up torque:	0.8 Ncm (20 °C)
Operating torque:	0.6 Ncm (20 °C)
Maximum operating speed:	9,000 /min <sup>1)</sup>
Moment of inertia of the rotor:	40 gcm <sup>2</sup>
Bearing lifetime:	3.0 x 10 <sup>9</sup> revolutions
Max. angular acceleration:	500,000 rad/s <sup>2</sup>
Permissible movement axial static/dynamic:	± 0.5 mm, ± 0.2 mm
Permissible movement radial static/dynamic:	± 0.3 mm, ± 0.1 mm

<sup>1)</sup> Self warming of 3.3 K per 1000 revolutions/min when applying note working temperature range

## Electrical data

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Power consumption:	0.5 W (without load)
Operating voltage range:	4.5 V DC ... 32 V DC
Load current max.:	30 mA
Maximum output frequency:	600 kHz
Reference signal, position:	90 °, electronically, gated with A and B
MTTFd: mean time to dangerous failure:	250 a (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

## Interfaces

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Electrical interface:	Connector M23, 12-pin, radial
Interface signals:	A, B: digital differential, Clock +, Clock -, Data +, Data- <sup>1)</sup>
Clock frequency:	2 MHz
SET (electronic adjustment):	H-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)
CW/CCW (counting sequence when turning):	L-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)

<sup>1)</sup>

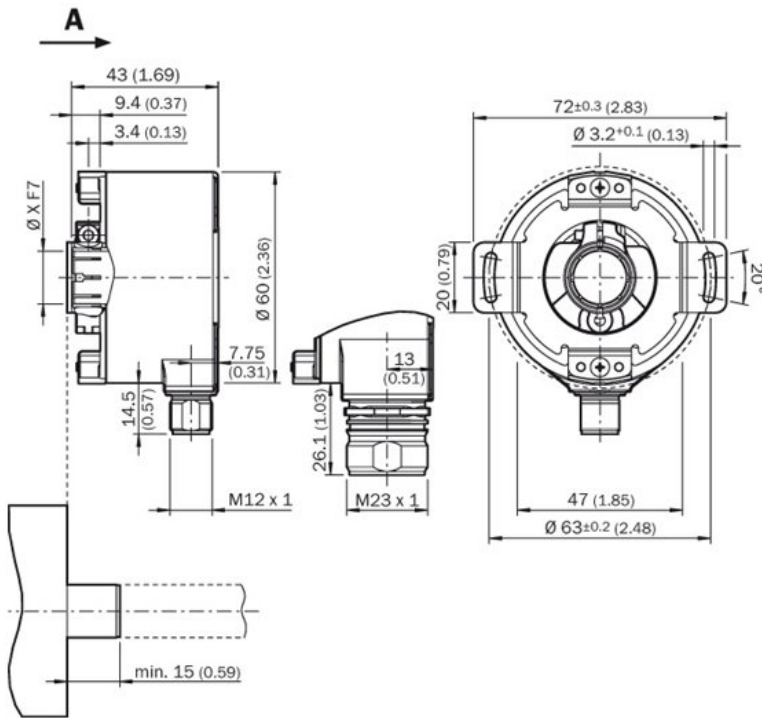
## Ambient data

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EMC:	(according to EN 61000-6-2 and EN 61000-6-3) <sup>1)</sup>
Enclosure rating:	IP 65 (according to IEC 60529), IP 65 (according to IEC 60529), shaft side
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-30 °C ... 100 °C
Storage temperature range:	-40 °C ... 100 °C, without package
Resistance to shocks:	70 g (according to EN 60068-2-27)
Resistance to vibration:	30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

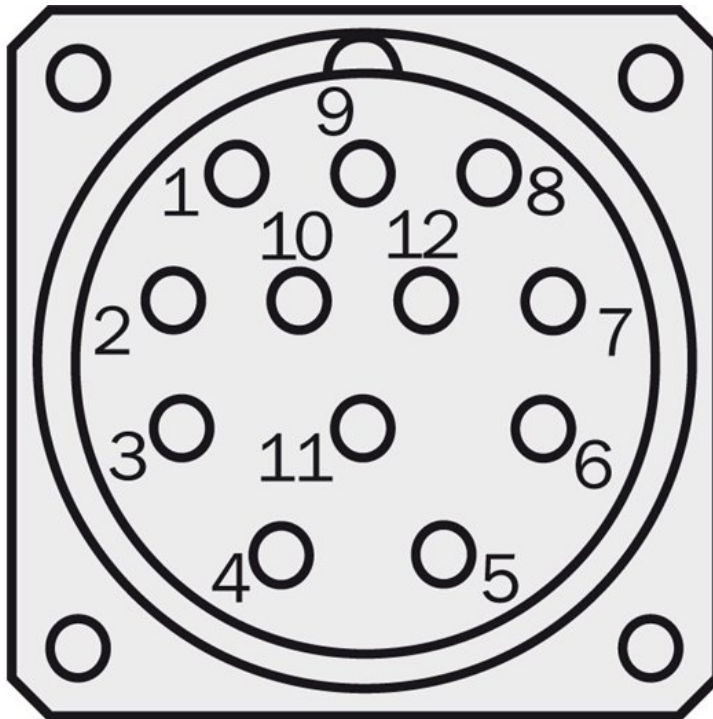
<sup>1)</sup> <sup>2)</sup> With mating connector fitted

**Dimensional drawing**



[1] Cable diameter = 5,6 mm  
 +/- 2 mm Bending radius = 30 mm

**PIN assignment**



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