

AFS60I-S4PK262144

AFS/AFM60 Inox

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

| Type | Part no. |
|-------------------|----------|
| AFS60I-S4PK262144 | 1084008 |

Other models and accessories → www.sick.com/AFS_AFM60_Inox

Detailed technical data

Performance

| | |
|---|----------------------|
| Number of steps per revolution (max. resolution) | 262,144 (18 bit) |
| Error limits G | 0.03° ¹⁾ |
| Repeatability standard deviation σ_r | 0.002° ²⁾ |

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

²⁾ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

| | |
|---|--|
| Communication interface | SSI |
| Initialization time | 50 ms ¹⁾ |
| Position forming time | < 1 μ s |
| SSI | |
| Code type | Gray |
| Code sequence parameter adjustable | CW/CCW (V/R) |
| Clock frequency | 2 MHz ²⁾ |
| Set (electronic adjustment) | H-active (L = 0 - 3 V, H = 4,0 - U _s V) |
| CW/CCW (counting sequence when turning) | L-active (L = 0 - 1,5 V, H = 2,0 - U _s V) |

¹⁾ Valid positional data can be read once this time has elapsed.

²⁾ SSI max. clock frequency 2 MHz, and min. LOW level (Clock+): 500 ns.

Electrical data

| | |
|------------------------|------------------------------|
| Connection type | Cable, 8-wire, radial, 1.5 m |
| Supply voltage | 4.5 ... 32 V DC |
| | Cable, 8-wire |

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

| | |
|--|-------------------------|
| Power consumption | ≤ 0.7 W (without load) |
| Reverse polarity protection | ✓ |
| MTTFd: mean time to dangerous failure | 250 years ¹⁾ |

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

| | |
|---|---|
| Mechanical design | Solid shaft, face mount flange |
| Shaft diameter | 10 mm |
| Shaft length | 19 mm |
| Weight | 0.5 kg ¹⁾ |
| Shaft material | Stainless steel V2A |
| Flange material | Stainless steel V2A |
| Housing material | Stainless steel V2A |
| Start up torque | 1 Ncm |
| Operating torque | 0.5 Ncm |
| Permissible Load capacity of shaft | 80 N / radial 40 N / axial |
| Moment of inertia of the rotor | 6.2 gcm ² |
| Bearing lifetime | 3.0 x 10 ⁹ revolutions |
| Angular acceleration | ≤ 500,000 rad/s ² |
| Operating speed | ≤ 9,000 min ⁻¹ ²⁾ |

¹⁾ Relates to devices with male connector connection.

²⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| | |
|--------------------------------------|---|
| EMC | According to EN 61000-6-2 and EN 61000-6-3 ¹⁾ |
| Enclosure rating | IP67, shaft side IP67, housing side, male connector connection ²⁾ IP67, housing side, cable connection |
| Permissible relative humidity | 90 % (condensation of the optical scanning not permitted) |
| Operating temperature range | -40 °C ... +100 °C ³⁾ -30 °C ... +100 °C ⁴⁾ |
| Storage temperature range | -40 °C ... +100 °C, without package |
| Resistance to shocks | 100 g, 6 ms (according to EN 60068-2-27) |
| Resistance to vibration | 10 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6) |

¹⁾ EMC according to the standards quoted is achieved if shielded cables are used.

²⁾ With mating connector fitted.

³⁾ Stationary position of the cable.

⁴⁾ Flexible position of the cable.

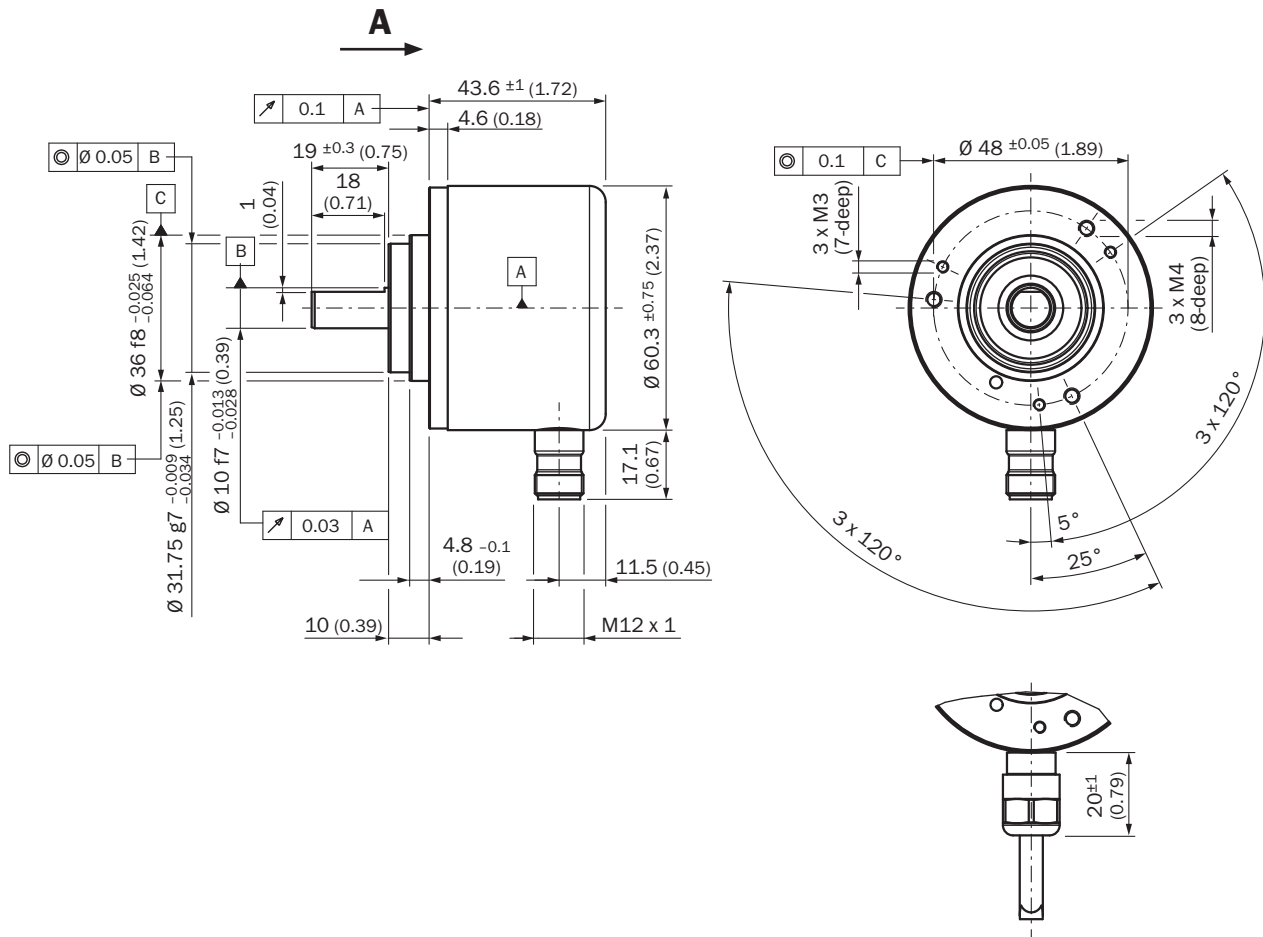
Classifications

| | |
|---------------------|----------|
| ECl@ss 5.0 | 27270502 |
| ECl@ss 5.1.4 | 27270502 |
| ECl@ss 6.0 | 27270590 |

| | |
|-----------------------|----------|
| ECl@ss 6.2 | 27270590 |
| ECl@ss 7.0 | 27270502 |
| ECl@ss 8.0 | 27270502 |
| ECl@ss 8.1 | 27270502 |
| ECl@ss 9.0 | 27270502 |
| ECl@ss 10.0 | 27270502 |
| ECl@ss 11.0 | 27270502 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

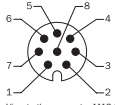
Dimensional drawing (Dimensions in mm (inch))

Solid shaft, face mount flange



PIN assignment

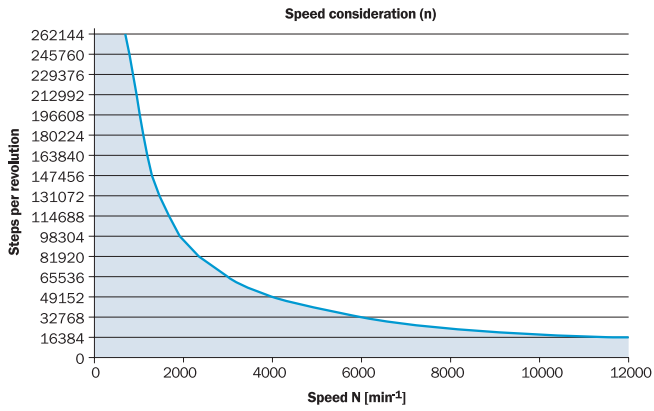
M12 male connector, 8-pin and cable connection, cable 8-wire, SSI/Gray



View to the connector M12 8-pin fitted to the encoder body

| PIN, 8-pin, M12 connector | Color of wires, cable outlet | Signal | Explanation |
|---------------------------|------------------------------|-----------------|---|
| 1 | Brown | Data- | Interface signals |
| 2 | White | Data+ | Interface signals |
| 3 | Black | CW/CCW | Counting sequence when turning |
| 4 | Pink | SET | Electronic adjustment |
| 5 | Yellow | Clock+ | Interface signals |
| 6 | Lilac | Clock- | Interface signals |
| 7 | Blue | GND | Ground connection |
| 8 | Red | +U _i | Supply voltage |
| | | Screen | Screen connected to housing on side of encoder. Connected to ground on side of control. |

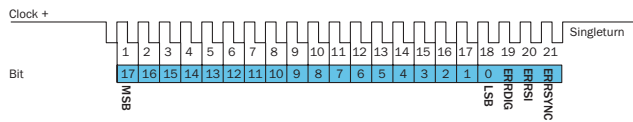
Maximum revolution range



The maximum speed is also dependent on the shaft type.

Diagrams

SSI data format singleturn



Bit 1–18: Position Bits

- LSB: Least significant Bit
- MSB: Most significant Bit

Bit 19–21: Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

The evaluation of the error bits has to be realized in the PLC.

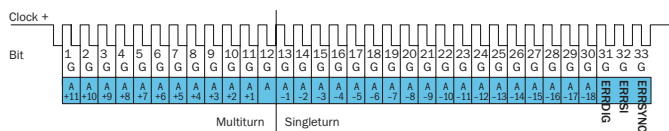
The provided error bits don't have to be used by the PLC compulsorily.

Example

If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

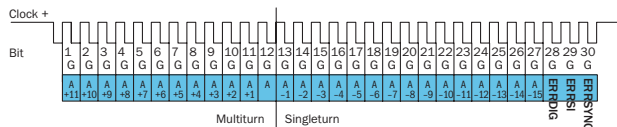
SSI data format multiturn

30 Bits



- Bit 1–12: Position Bits multiturn
- Bit 13–30: Position Bits singleturn
- Bit 31–33: Error Bits

27 Bits



- Bit 1–12: Position Bits multiturn
- Bit 13–27: Position Bits singleturn
- Bit 28–30: Error Bits

Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

Example

If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

Electrical interfaces sine 0.5 V_{pp}

| Power supply | Output |
|---------------|--------------------------|
| 4.5 ... 5.5 V | Sine 0.5 V _{pp} |

Signal before differential generation at load 120 Ω at U_s = 5 V

Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



| Interface signals Sin, $\overline{\text{Sin}}$, Cos, $\overline{\text{Cos}}$ | Signal before differential generation at load 120 Ω | Signal offset |
|---|---|---------------|
| Analog differential | 0.5 V _{pp} ± 20 % | 2.5 V ± 10 % |

Signal after differential generation at load 120 Ω at U_s = 5 V

Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



Electrical interfaces HTL/TTL

Incremental pulse diagram for clockwise rotation of the shaft looking in direction "A", see dimensional drawing



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